Version 2.0

Operating Instructions



Active Electrode TF-IR BL







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Table of Contents

	0.1	Publica	ation Statement	4
	0.2	Genera	al Notes	5
	0.3		Directive 2002/96/EC Law on Electrical and nic Equipment	6
1	In	ntroducti	ion	7
	1.1	Descrip	otion	7
	1.2	Device	Layout and Button Assignment	8
	1.3	Display	/Symbols	9
2	В	asic Fur	nctions	10
	2.1	Display	in Measuring Mode	10
	2.2	Setting	Menus	11
	2	.2.1	Measurement Menu (Main Menu)	11
	2	.2.2	Measuring Mode Selection Menu	12
	2	.2.3	Laser Pointer / EM Settings	14
	2	.2.4	Maximum Value Display	15
	2	0 E	Minimum Value Dianlay	10
	2	.2.5	Minimum Value Display	10



3	Specifications			18
	3.1	Technic	cal Data	18
	3.2	Prohibit	ted Environmental Conditions	18
	3.3	Measu	ing Ranges and Sensor Accuracy	19
4	Ap	oplicatio	on Notes	20
	4.1	Measu	ing Air Humidity	20
	4.1	1.1	Absolute Humidity	20
	4.1	1.2	Moisture Saturation	20
	4.	1.3	Relative Air Humidity	21
	4.	1.4	Equilibrium Wood Moisture Content (EMC)21
	4.2	Measu	ing Air Temperature	21
	4.2	2.1	Dew Point Temperature	22
	4.2	2.2	Dew Point Temperature vs. Air Temperature Rel. Humidity for Condensation Calculation	
	4.3		I Information on Infrared Temperature Mea logy (IR)	0
	4.4	Measu	ing Using an IR Sensor	24
	4.5	Emissio	on Ratio	26
	4.6	Measu	ement Spot Size	27
5	Ap	opendix		28
	5.1	Emissiv	ity Table	28
	5.2	Genera	I Concluding Remarks	29



0.1 Publication Statement

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GANN Mess- u. Regeltechnik GmbH, Gerlingen, Germany, 07.11.2014



0.2 General Notes

This measuring device fulfils the requirements of the applicable European and national directives (2004/108/EC) and standards (EN61010). Appropriate declarations and documentation are held by the manufacturer. To ensure trouble-free operation of the measuring device and operational reliability, the user must carefully read the operating instructions. The measuring device may only be operated under the climatic conditions specified. These conditions can be found in Chapter 3.1 "Technical data". This measuring device may likewise only be used under the conditions and for the purposes it was designed for. Operational reliability and functionality are no longer ensured if the device is modified or adapted. Gann Mess- u. Regeltechnik GmbH is not liable for any damage arising from such modifications or adaptations. The risk is borne by the user alone.

Laser equipment warning:



This unit is equipped with a Class 2 laser. Never direct this laser beam into the eyes, neither directly nor indirectly through reflecting surfaces. Laser radiation may cause irreversible damage to the eyes. When measurements are performed with

humans being nearby, the laser beam must be disabled.

• The notes and tables in these instructions on permitted or normal humidity conditions in practice and the general definitions of terms have been taken from the specialist literature. No responsibility can therefore be taken by the manufacturer for the correctness of this information. The conclusions to be drawn from the measurement results are related to the individual conditions and the knowledge drawn from professional experience for each user.



- The measuring device maybe operated in residential and commercial areas, as the stricter class B for emitted interference (EMC) has been adhered to.
- The device may not be operated in the immediate area of medical equipment (heart pacemakers, etc.).
- The measuring device mayonly be properly used as described in these instructions.
- Keep the device and accessories out of the reach of children!

Gann Mess-u. Regeltechnik GmbH accepts no liability for damage resulting from non-adherence to the operating instructions or by not taking proper care during transport, storage or operation of the device, even if this requirement for care is not specifically addressed in the operating instructions.

0.3 WEEE Directive 2002/96/EC Law on Electrical and Electronic Equipment

Disposal of packaging, battery, and device must be undertaken in accordance with the legal requirements at a recycling centre.

The device was manufactured after 1 May, 2010.



1 Introduction

1.1 Description

The active electrode TF-IR BL is a combined electrode that can be used to simultaneouslyperform climate measurements (air humidityand temperature) and infrared surface temperature measurements.

This combination of the different measuring techniques enables the active electrode TF-IR BL to be used for quickly and reliably assessing dew point undershoots or determining borderline conditions on surfaces such as walls, ceilings, floors as well as on window or door lintels.

When using the unit in due time, mildew formation maybe prevented and occurrence of moistening caused by condensation may be assessed reliably.

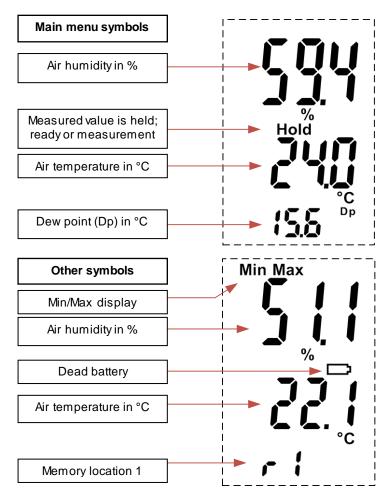


1.2 Device Layout and Button Assignment





1.3 Display Symbols

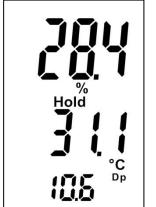


Active electrode TF-IR BL



2 Basic Functions

2.1 Display in Measuring Mode



Measured value in %

"Hold" symbol signals readiness to make a measurement

Measured temperature in °C

Calculated dew point (Dp) in °C

Figure 2-1: measuring mode

A measurement process is started by pressing the **"M"** button. During the measurement process, the "%" symbol blinks and the values adapt to the surrounding conditions. After releasing the "M" button, the "%" symbol is displayed steadily and the "Hold" symbol also appears.

The device is now in Ready mode.

Press the "M" button again to start a new measurement.

Approx. 40 seconds after releasing the measurement button, the device automatically switches off to save battery power. When the device is switched on again, the last value measured is shown on the display.



2.2 Setting Menus

When the **"Up**" or **"Down"** buttons are pressed in *Ready mode*, the various setting menus are shown one after another:

- 1. **Measurement menu** (*Ready mode*): The measuring process can be carried out here
- 2. **Measuring mode selection:** Here you can specify the measuring mode (section 2.3.2)
- 3. Laser pointer / EM menu: This menu can be used to disable/enable the laser pointer and to set the emissivity (EM factor).
- 4. **Maximum value display:** The largest value measured is shown here (section 2.3.3)
- 5. **Minimum value display:** The smallest value measured is shown here (section 2.3.4)
- 6. **Saved menu:** The last 5 values measured can be called here (section 2.3.5)

2.2.1 Measurement Menu (Main Menu)

The last measurement with the note "Hold" is shown here.

In this menu, a new measurement can be started by pressing the "**M**" button.

During the measuring process, the "**Hold**" symbol disappears from the display. After releasing the "**M**" button, the measured value is saved. The "**Hold**" symbol is displayed again.

If the new measured value is larger than the previous maximum value, "**Max**" flashes on the display. If the value is not to be saved, the "**M**" button must be pressed *briefly*. If the value is not to be saved, a new measurement is started with a *long* press on the "**M**" button without changing the previous maximum values.



2.2.2 Measuring Mode Selection Menu

In this menu, the various modes for the TF-IR BL may be set. The currently active mode is selected with a short press of the M button. The mode then begins to blink. Now a mode can be selected with the Up and Down buttons and confirmed with a short press on the M button.

The TF-IR BL has 4 different setting modes that may be scrolled top-down in the following order by pressing the "Down" button:

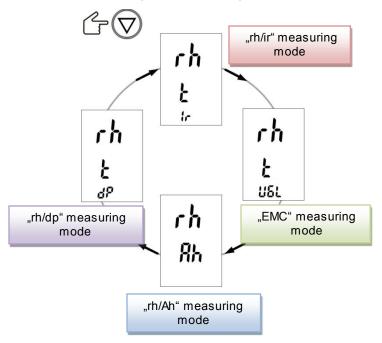


Figure 2-3: measuring mode selection menu



The selected mode changes the displayof the measurement menu. Depending on the mode, the appropriate physical dimension is also displayed. The individual menus are scrolled top-down bypressing the "Down" button.



"rh/ir" measuring mode (relative humidity, IR temperature): *Relative humidity (in %), air temperature (in °C),* and the *IR surface temperature measured (in °C)* are displayed.



"EMC" measuring mode (equilibrium wood moisture content, EMC):

Equilibrium wood moisture content is the moisture content adopted by the wood when it is exposed to constant climate (constant air humidity and constant temperature) for sufficiently long time.



"rh/Ah" measuring mode (relative/absolute humidity): the relative humidity (in %) and the absolute humidity (in g/m^3 i.e. grammes of water in $1m^3$ of air) are displayed.



"rh/dp" measuring mode (relative humidity, dew point temperature):

Relative humidity (in %), air temperature (in °C), and dew point temperature (dp) (in °C) are displayed.

Information and explanations on the individual measuring modes can be found in Chapter 4 "Application instructions".



2.2.3 Laser Pointer / EM Settings

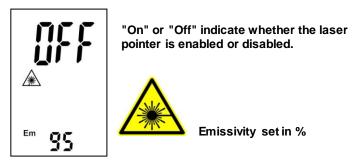


Figure 2-2: laser pointer

When the default settings for emissivity (EM factor) and laser pointer are to be changed, the "**M**" button must be pressed *momentarily*. Emissivity (EM factor) and laser pointer displaynow start flashing.

EM factor adjustment:

Using the **"Up"** or **"Down"** buttons, emissivity (EM factor) may now be set between 20% and 100% in 1 unit increments or decrements. The setting is saved by again pressing the **"M"** button *momentarily* (< 1s).

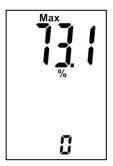
The emissivity table is found in the Appendix.

Laser pointer adjustment:

By holding the "**M**" button depressed for longer than 2 seconds, the status of the laser pointer maybe changed from "Off" to "On" and vice versa. To save the status selected and to return to the main menu, the "**M**" button must be pressed *momentarily* (< 1s).



2.2.4 Maximum Value Display



In this menu, the maximum air humidity value measured in a measurement sequence is displayed. Only the "rh" relative humidity is displayed.

If a maximum value is to be deleted, the displayed value must be selected with a *short* press on the "**M**" button.

The value flashes and can now be deleted using a *long* press on the "**M**" button.

Figure 2-3: maximum value menu

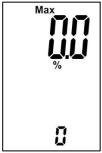


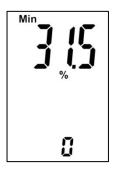
Figure 2-4: deleted max. value

Afterwards, only the "Max" symbol and the % symbol are still blinking. Using another *momentary* press on "M" button, the entry is confirmed and the device returns to the Ready mode.

Using the "**M**" button, a new measurement can then be carried out immediately.



2.2.5 Minimum Value Display



In this menu, the minimum air humidity value measured in a measurement sequence is displayed. Only the "rh" relative humidity is displayed.

If a minimum value is to be deleted, the displayed value must be selected with a *short* press on the "**M**" button.

The value flashes and can now be deleted using a *long* press on the "**M**" button.

Figure 2-5: minimum value menu

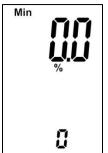


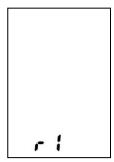
Figure 2-6: deleted min. value Afterwards, only the "Min" symbol and the % symbol are still blinking. Using another *momentary* press on "M" button, the entry is confirmed and the device returns to the Ready mode.

Using the "**M**" button, a new measurement can then be carried out immediately.



2.2.6 Memory Menu

In this menu, the last 5 measured values are saved. The view and the respective units depend on the measuring mode selected.



The memory location number "r1" is displayed for approx. 1 second and then the last measured saved value is displayed that is saved at this location.

You can recognize saved values as there is no "Hold" symbol in the display.

Figure 2-7: memory location r1

As soon as you select the saved menu, the memory location number "r1" is displayed for approx. 1 second, and then the last measured saved value contained there is displayed.

The last 5 measured values are automatically saved and stored in memory locations "r1" to "r5". The last measured value is in memory location "r1". This is a ring buffer. As soon as the sixth measured value is recorded, the "first" (first measured) measured value is automatically removed from the buffer.

By *momentarily* pressing the **"M"** button, the next memorylocation "r2" is selected and the value contained there is displayed. After reaching the 5th memorylocation, the first one is shown again.

The menu can be exited using the "Up" or "Down" buttons.



3 Specifications

3.1 Technical Data

Display:	3-line display
Display resolution:	0,1 %
Storage conditions:	+ 5 to + 40 °C
	- 10 to + 60 °C (short-term)
Operating conditions:	0 to + 50 °C
	- 10 to + 60 °C (short-term)
Dimensions:	160 x 40 x 30 (L x W x H) mm
Weight:	approx. 164 g

3.2 Prohibited Environmental Conditions

- Condensation, air humidity continuously too high (> 85 %) and wetness
- Permanent presence of dust and combustible gases, fumes or solutions
- Ambient temperatures continuously too high (> +50 °C)
- Ambient temperatures continuously too low (< 0 °C)



3.3 Measuring Ranges and Sensor Accuracy

Measuring ranges:

Air:

Humidity: <i>0 to 100% r.F.</i>	20 to 80% r.H. (<u>+</u> 3% r.F.)
Temperature: -20 to +80 °C	-10 to +60 °C (<u>+</u> 0.5 °C)
IR:	
Temperature: -40 to +380 ℃	0 to +60 °C (<u>+</u> 0.5 °C)



4 Application Notes

On the following pages, you will find information on the various measuring modes of the active electrode TF-IR BL (Sections 4.1, 4.2 and 4.3) and on how to use the unit.

4.1 Measuring Air Humidity

4.1.1 Absolute Humidity

The amount of water vapour in g/m³ in the air is termed absolute humidity. The amount of water vapour cannot exceed a fixed specified amount.

Humidity (abs.) = $\frac{Mass \ of \ water \ (g)}{Air \ volume \ (m^3)}$

4.1.2 Moisture Saturation

Moisture saturation is the maximum amount of water that can be contained in a certain volume of air. The higher temperature the larger the amount of water that can be held in the air.

$$Humidity (sat.) = \frac{Max.mass of water (g)}{Air volume (m^3)}$$



4.1.3 Relative Air Humidity

The relative air humidity is the ratio of the actual water vapour content (absolute humidity) to the moisture saturation. The relative humidity is heavily dependent on the temperature.

 $Humidity (rel.) = \frac{Humidity (abs.)x \, 100 \, (\%)}{Humidity (sat.)}$

4.1.4 Equilibrium Moisture Content (EMC)

The device is able to display relative humidity, air temperature and the equilibrium moisture content of wood simultaneously.

This makes it easier for parquet recliners and interior designers to evaluate whether timber components can be exposed to the existing climate, or whether damage such as cracking, shrinkage or swelling is to be feared.

The equilibrium moisture content is the moisture content that wood will finally reach when it is exposed to a constant climate (i.e. constant humidity and constant temperature) long enough.

4.2 Measuring Air Temperature

Handling

For particularly precise measurements, particularly for temperatures under +10 °C or above +40 °C, or for significant differences between the temperature of the sensor or measuring device and the surrounding atmosphere, the device should be exposed to the surrounding atmosphere of the measurement location for approx. 10-15 minutes or until the temperature has equalised. The measuring range of -40 °C to +80 °C only applies to the sensor tip (length of the protective/filter cap). The measuring *Active electrode TF-IR BL* 21



device may only be exposed to temperatures above 50 °C for short periods. False measurements can arise from shielding with body parts (e.g. hand) as well as blowing or speaking/breathing in the direction of the sensor.

The setting time of the air temperature sensor in moving air is approx. 3 minutes for 90 % of the temperature difference.

The air temperature sensor adapts to the surrounding temperature even when stored (not switched on).

4.2.1 Dew Point Temperature

The dew point is the temperature at which the air is saturated with water vapour. Condensation occurs below this temperature. The dew point generallylies below the air temperature, except with 100 % r.h, where both temperatures are the same.

The dew point is dependent on the air temperature and water vapour partial pressure and equal to the temperature whose saturation pressure is equal to the water vapour partial pressure present. The water vapour partial pressure is calculated as follows:

 $Water \ vapour \ pressure = \frac{rel.humidity \ x \ water \ vapour \ sat.press.}{100}$

Further information can be found on the Internet.

Air temperature	Dew point temperature in °C at a relative humidity of:							
°C	30%	40%	50%	60%	70%	80%	90%	Saturation moisture = amount of water
	°C	°C	°C	°C	°C	°C	°C	in g/m ³
30	10,5	14,9	18,5	21,2	24,2	26,4	28,5	30,4
28	8,7	13,1	16,7	19,5	22,0	24,2	26,2	27,2
26	7,1	11,3	14,9	17,6	19,8	22,3	24,2	24,4
24	5,4	9,5	13,0	15,8	18,2	20,3	22,2	21,8
22	3,6	7,7	11,1	13,9	16,3	18,4	20,3	19,4
20	1,9	6,0	9,9	12,0	14,3	16,5	18,3	17,3
18	0,2	4,2	7,4	10,1	12,4	14,5	16,3	15,4
16	-1,5	2,4	5,6	8,2	10,5	12,5	14,3	13,6
14	-3,3	-0,6	3,8	6,4	8,6	10,6	14,4	12,1
12	-5,0	-1,2	1,9	4,3	6,6	8,5	10,3	10,7
10	-6,7	-2,9	0,1	2,6	4,8	6,7	8,4	9,4
8	-8,5	-4,8	-1,6	0,7	2,9	4,8	6,4	8,3
6	-10,3	-6,6	-3,2	-1,0	0,9	2,8	4,4	7,3
4	-12,0	-8,5	-4,8	-2,7	-0,9	0,8	2,4	6,4
2	-13,7	-10,2	-6,5	-4,3	-2,5	-0,8	0,6	5,6
0	-15,4	-12,0	-8,1	-5,6	-3,8	-2,3	-0,9	4,8

4.2.2 Dew Point Temperature vs. Air Temperature and Rel. Humidity for Condensation Calculation



4.3 General Information on Infrared Temperature Measuring Technology (IR)

Anybody having a temperature above "absolute zero" (= 0° K or - 273°C) emits infrared radiation that is also referred to as thermal radiation. Taking into account the emission ratio, the intensity of this thermal radiation is considered to be a measure for the surface temperature. The infrared sensing head receives the emitted thermal radiation in a non-contact manner and converts it into a voltage signal.

Benefits over contact measurement using mechanical sensor:

- Very fast response or measuring time.
- No heat removal at the object being measured.
- No damage or contamination of the measuring surface.
- Live or moving parts may be measured.

4.4 Measuring Using an IR Sensor

When measurements are carried out in the immediate vicinity of hot or cold parts (exhaust pipe, radiant heater, or freezing/chiller unit) for more than 10 seconds in duration, the measured value maybe distorted. After approximately 10 minutes waiting time (temperature equalisation of sensor housing and ambient temperature), the measurement maybe repeated. To obtain exact measured values, the temperature of the measuring unit must have approximated the respective ambient temperature.

To avoid measurement errors and to prevent the unit from being damaged, you should...

- ... not press the sensor opening of the measuring transducer directly onto the object to be measured.
- ... not measure in air that contains steam or is heavily contaminated.



- ... not measure through very hot air (shimmering heat).
- ...not measure objects that are exposed to direct sunlight (shadow these objects).
- ...not measure objects located in immediate vicinity of equipment radiating large amounts of heat (stop thermal radiation).
- ...not expose this high-quality measuring unit to very high or low temperatures (e.g. transporting the unit in the boot).
- ... not expose the unit to high air humidity (condensing).
- ... not measure in immediate vicinity of sources of electromagnetic or electrostatic energy (RF generators, electric motors, ignition voltages etc.).



4.5 Emission Ratio

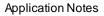
The active electrode TF-IR BL provides manual adjustment of the emission ratio between 20% and 100%. The emissivity table is found in the Appendix.

By default, the measuring unit is set to an emission ratio of 95%. This value is valid for the majority of construction materials, plastic, textile or paper types, and non-metallic surfaces. The following summary is for estimating the emissivity that depends, among others, on brilliance and roughness of the material to be measured. Emissivity is reduced on plane and glossy surfaces while it is increased on rough and matt surfaces. Since an emissivity ranging from 10% to 90% for metals is sufficient depending on the surface (glossy, oxidised, or corroded), exact measurements cannot be carried out. For metals or glossy metallic surfaces and objects with other emissivity values, we therefore recommend using special labels (IR 30/E95 **item no. 5833**) that are made of paper and provide a factor of 95%.

Mathematical correction of the temperature measured value using emissivity requires the ambient temperature and the coefficient of the temperature equalisation between measuring transducer and ambient temperature to be known.

The following applies to the correction:

$$\frac{(T_{Display} - T_{Ambience}) * 100}{Emission \ ratio \ (\%)} + T_{ambience} = T_{Meas. \ obj.}$$



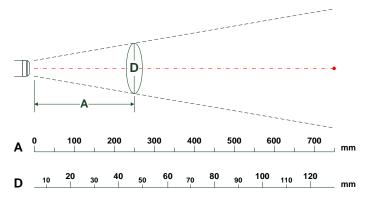


4.6 Measurement Spot Size

The measurement spot diameter depends on the distance and is 5 mm immediately ahead of the measuring transducer opening. A larger distance (A) between the measuring device and the object to be measured proportionally increases the measuring spot diameter (D) in a ratio of approximately 6:1. With a distance (A) of 250 mm, the measurement spot diameter (D) is 46 mm. For the measuring distance (A) between the surface to be measured and sensor, we recommend using 20 to 50 mm. The respective diameter can be obtained from the figure below.

A = Distance to the object to be measured

D = Measurement spot diameter





5 Appendix

5.1 Emissivity Table

Material	Condition	Temperature*	EM factor
Aluminium**	Non-oxidised	25	2
		100	3
	Heavily oxidised	100	20
	Highly polished	100	9
	Slightly polished	100	18
Asbestos			95
Asphalt			95
Lead**	Oxidised		28
	Uncoated	230	6
Stainless	Matt		60
steel**	Oxidised		16
Ice	Surface		100
Iron**	Enamelled		88
	Oxidised		80
	Corroded		64
	Nickel-plated, matt		12
	Nickel-plated, polished		6 27
Soil	Zinc-plated Dry		92
301	Humid		95
Paint	Black, matt		96
1 cint	Black, glossy		92
	Other colours		95
	Clear coat		87
Gypsum	Bulk material		81
	Processed		91
Glass	Plane		94
	Convex	100	80
	Concave	100	82
Gold**			2
Graphite			98



Material	Condition	Temperature*	EM factor
Rubber	Dark		95
	Bright		86
	Hard		88-95
	Soft		67-84
Casting**	Cast iron		94
	Cast iron, polished		21
Skin		38	98
Wood			80-90
Lime			30-40
Lime mortar			93
Copper**	Highly polished		7
	Heavily oxidised		78
Marble			93
Brickwork			95
Brass**	Polished		5
	Oxidised		60
Nickel**	Polished		5
	Oxidised		32
Porcelain			93
Plaster	Lime plaster		92
Sand			90
Snow		-10	85
	Smooth		95
Bolts**			85
Silv er**			3
Steel**	Oxidised		80
	Rolled		24
Tar			83
Water			96
Brick	Clay brick		93
Tin**			5

*(No value given in the "Temperature" field indicates, that the values show n are valid for a nominal temperature of 20 °C.)

(Because of their surface, metals cannot be measured precisely (e.g.: oxidised/polished surface \rightarrow EM factor between 2 and 100%). We therefore recommend using the paper label (IR 30/E95 **item no. 5833) showing a factor of 95%. This label provides for exact object temperature measurements.

TF-IR BL



5.2 General Concluding Remarks

The notes and tables in these operating instructions on permitted or normal humidity conditions in practice and the general definitions of terms have been taken from the specialist literature. No responsibility can therefore be taken by the manufacturer of the measuring device for the correctness of this information.

The conclusions to be drawn from the measurement results are related to the individual conditions and the knowledge from professional experience for each user. In cases of doubt, for example concerning the permitted moisture content in coating or screed substrates when laying floor coverings, it is recommended to contact the manufacturer of the coating or floor covering and to take account of the recommendations of trade organisations.

Guarantee conditions

Gann Mess-u. Regeltechnik GmbH shall rectify material or manufacturing defects at no cost by repair or replacement of the defective parts at its choice that occur within six months of purchase or one year of dispatch from the factory, whichever period ends first. Neither the replacement nor the repair of a part constitutes a new guarantee or an extension of the original guarantee.

Batteries and other parts subject to wear such as cables or filter material are excluded from the guarantee.



When claiming under the guarantee, the device must be sent postage-free to Gann Mess-u. Regeltechnik GmbH or the supplier with details of the claim and accompanied byproof of purchase. The guarantee is void if repairs or other manipulations have been carried out by the owner or third party.

Gann Mess-u. Regeltechnik GmbH accepts no liabilityfor damage or malfunctions caused by improper or incorrect handling or storage of the device. Gann Mess-u. Regeltechnik GmbH will on no account accept liabilityfor damage, lost profit, lost usage or other consequential damage that arise from the use of the product or the inability to use it.

-Subject to technical changes-



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